

Stat 709: Mathematical Statistics

Lecture 2

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Lecture 2: Product measure, measurable function and distribution

Product space

$\mathcal{I} = \{1, \dots, k\}$, k is finite or ∞

$\Gamma_i, i \in \mathcal{I}$, are some sets

$\prod_{i \in \mathcal{I}} \Gamma_i = \Gamma_1 \times \dots \times \Gamma_k = \{(\mathbf{a}_1, \dots, \mathbf{a}_k) : \mathbf{a}_i \in \Gamma_i, i \in \mathcal{I}\}$

$\mathcal{R} \times \mathcal{R} = \mathcal{R}^2, \mathcal{R} \times \mathcal{R} \times \mathcal{R} = \mathcal{R}^3$

Product σ -field

Let $(\Omega_i, \mathcal{F}_i), i \in \mathcal{I}$, be measurable spaces

$\prod_{i \in \mathcal{I}} \mathcal{F}_i$ is not necessarily a σ -field

$\sigma(\prod_{i \in \mathcal{I}} \mathcal{F}_i)$ is called the *product σ -field* on the *product space* $\prod_{i \in \mathcal{I}} \Omega_i$

$(\prod_{i \in \mathcal{I}} \Omega_i, \sigma(\prod_{i \in \mathcal{I}} \mathcal{F}_i))$ is denoted by $\prod_{i \in \mathcal{I}} (\Omega_i, \mathcal{F}_i)$

Example: $\prod_{i=1, \dots, k} (\mathcal{R}, \mathcal{B}) = (\mathcal{R}^k, \mathcal{B}^k)$

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Product measure

Consider a rectangle $[a_1, b_1] \times [a_2, b_2] \subset \mathcal{R}^2$.

The usual area of $[a_1, b_1] \times [a_2, b_2]$ is

$$(b_1 - a_1)(b_2 - a_2) = m([a_1, b_1])m([a_2, b_2])$$

Is $m([a_1, b_1])m([a_2, b_2])$ the same as the value of a measure defined on the product σ -field?

σ -finite

A measure ν on (Ω, \mathcal{F}) is said to be σ -finite iff there exists a sequence $\{A_1, A_2, \dots\}$ such that $\cup A_i = \Omega$ and $\nu(A_i) < \infty$ for all i

Any finite measure (such as a probability measure) is clearly σ -finite

The Lebesgue measure on \mathcal{R} is σ -finite, since $\mathcal{R} = \cup A_n$ with $A_n = (-n, n)$, $n = 1, 2, \dots$

The counting measure is σ -finite if and only if Ω is countable

The measure $\nu(A) = \infty$ unless $A = \emptyset$ is not σ -finite

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Proposition 1.3 (Product measure theorem)

Let $(\Omega_i, \mathcal{F}_i, \nu_i)$, $i = 1, \dots, k$, be measure spaces with σ -finite measures, where $k \geq 2$ is an integer.

Then there exists a unique σ -finite measure on the product σ -field $\sigma(\mathcal{F}_1 \times \dots \times \mathcal{F}_k)$, called the *product measure* and denoted by $\nu_1 \times \dots \times \nu_k$, such that

$$\nu_1 \times \dots \times \nu_k(A_1 \times \dots \times A_k) = \nu_1(A_1) \cdots \nu_k(A_k)$$

for all $A_i \in \mathcal{F}_i$, $i = 1, \dots, k$.

The joint c.d.f.

Let P be a probability measure on $(\mathcal{R}^k, \mathcal{B}^k)$.

The *joint c.d.f.* of P is defined by

$$F(x_1, \dots, x_k) = P((-\infty, x_1] \times \dots \times (-\infty, x_k]), \quad x_i \in \mathcal{R}$$

There is a one-to-one correspondence between probability measures and joint c.d.f.'s on \mathcal{R}^k

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Marginal c.d.f.

If $F(x_1, \dots, x_k)$ is a joint c.d.f., then

$$F_i(x) = \lim_{x_j \rightarrow \infty, j=1, \dots, i-1, i+1, \dots, k} F(x_1, \dots, x_{i-1}, x, x_{i+1}, \dots, x_k)$$

is a c.d.f. and is called the i th *marginal* c.d.f.

The c.d.f. and product measure

- Marginal c.d.f.'s are determined by their joint c.d.f.
- But a joint c.d.f. cannot be determined by k marginal c.d.f.'s.
- If

$$F(x_1, \dots, x_k) = F_1(x_1) \cdots F_k(x_k), \quad (x_1, \dots, x_k) \in \mathcal{R}^k,$$

then the probability measure corresponding to F is the product measure $P_1 \times \cdots \times P_k$ with P_i being the probability measure corresponding to F_i

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then the probability measure corresponding to F is the product measure $P_1 \times \cdots \times P_k$ with P_i being the probability measure corresponding to F_i

Measurable function

f : a function from Ω to Λ (often $\Lambda = \mathcal{R}^k$)

Inverse image of $B \subset \Lambda$ under f :

$$f^{-1}(B) = \{\omega \in \Omega : f(\omega) \in B\}.$$

The inverse function f^{-1} need not exist for $f^{-1}(B)$ to be defined.

$$f^{-1}(B^c) = (f^{-1}(B))^c \quad \text{for any } B \subset \Lambda$$

$$f^{-1}(\cup B_i) = \cup f^{-1}(B_i) \quad \text{for any } B_i \subset \Lambda, i = 1, 2, \dots$$

Let \mathcal{C} be a collection of subsets of Λ .

Define $f^{-1}(\mathcal{C}) = \{f^{-1}(C) : C \in \mathcal{C}\}$

Definition 1.3

Let (Ω, \mathcal{F}) and (Λ, \mathcal{G}) be measurable spaces.

Let f be a function from Ω to Λ .

f is called a *measurable function* from (Ω, \mathcal{F}) to (Λ, \mathcal{G}) iff $f^{-1}(\mathcal{G}) \subset \mathcal{F}$.

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Remarks

- f is measurable from (Ω, \mathcal{F}) to (Λ, \mathcal{G}) iff for any $B \in \mathcal{G}$, $f^{-1}(B) = \{\omega : f(\omega) \in B\} \in \mathcal{F}$; we don't care about whether $\{f(\omega) : \omega \in A\}$ is in \mathcal{G} or not, $A \in \mathcal{F}$.
- If \mathcal{F} is the collection of all subsets of Ω , then any function f is measurable.
- If f is measurable from (Ω, \mathcal{F}) to (Λ, \mathcal{G}) , then $f^{-1}(\mathcal{G})$ is a sub- σ -field of \mathcal{F} and is called the σ -field generated by f and denoted by $\sigma(f)$.
- $\sigma(f)$ may be much simpler than \mathcal{F}
- A measurable f from (Ω, \mathcal{F}) to $(\mathcal{R}, \mathcal{B})$ is called a Borel function.
- In probability and statistics, a Borel function is also called a random variable.
A random variable = a variable that is random?
- A random vector (X_1, \dots, X_n) is a function measurable from (Ω, \mathcal{F}) to $(\mathcal{R}^n, \mathcal{B}^n)$.
- (X_1, \dots, X_n) is a random vector iff each X_i is a random variable.

Indicator functions

The indicator function for $A \subset \Omega$ is:

$$I_A(\omega) = \begin{cases} 1 & \omega \in A \\ 0 & \omega \notin A. \end{cases}$$

For any $B \subset \mathcal{R}$,

$$I_A^{-1}(B) = \begin{cases} \emptyset & 0 \notin B, 1 \notin B \\ A & 0 \notin B, 1 \in B \\ A^c & 0 \in B, 1 \notin B \\ \Omega & 0 \in B, 1 \in B. \end{cases}$$

Then, $\sigma(I_A) = \{\emptyset, A, A^c, \Omega\}$ and I_A is Borel iff $A \in \mathcal{F}$

Note that $\sigma(I_A)$ is much simpler than \mathcal{F} .

Simple functions

Let A_1, \dots, A_k be measurable sets on Ω and a_1, \dots, a_k be real numbers. A simple function is

$$\varphi(\omega) = \sum_{i=1}^k a_i I_{A_i}(\omega),$$

Let A_1, \dots, A_k be a partition of Ω , i.e., A_i 's are disjoint and $A_1 \cup \dots \cup A_k = \Omega$.

Then the simple function φ with distinct a_i 's exactly characterizes this partition and $\sigma(\varphi) = \sigma(\{A_1, \dots, A_k\})$.

A simple function is nonnegative iff $a_i \geq 0$ for all i .

Proposition 1.4

Let (Ω, \mathcal{F}) be a measurable space.

- (i) f is Borel if and only if $f^{-1}(a, \infty) \in \mathcal{F}$ for all $a \in \mathcal{R}$.
- (ii) If f and g are Borel, then so are fg and $af + bg$, where a and b are real numbers; also, f/g is Borel provided $g(\omega) \neq 0$ for any $\omega \in \Omega$.

Simple functions

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Proposition 1.4 (continued)

- (iii) If f_1, f_2, \dots are Borel, then so are $\sup_n f_n$, $\inf_n f_n$, $\limsup_n f_n$, and $\liminf_n f_n$.

Furthermore, the set

$$A = \left\{ \omega \in \Omega : \lim_{n \rightarrow \infty} f_n(\omega) \text{ exists} \right\}$$

is an event and the function

$$h(\omega) = \begin{cases} \lim_{n \rightarrow \infty} f_n(\omega) & \omega \in A \\ f_1(\omega) & \omega \notin A \end{cases}$$

is Borel.

- (iv) Suppose that f is measurable from (Ω, \mathcal{F}) to (Λ, \mathcal{G}) and g is measurable from (Λ, \mathcal{G}) to (Δ, \mathcal{H}) .

Then the composite function $g \circ f$ is measurable from (Ω, \mathcal{F}) to (Δ, \mathcal{H}) .

- (v) Let Ω be a Borel set in \mathcal{R}^p .

If f is a continuous function from Ω to \mathcal{R}^q , then f is measurable.

Distribution (law)

Let $(\Omega, \mathcal{F}, \nu)$ be a measure space and f be a measurable function from (Ω, \mathcal{F}) to (Λ, \mathcal{G}) .

The *induced measure* by f , denoted by $\nu \circ f^{-1}$, is a measure on \mathcal{G} defined as

$$\nu \circ f^{-1}(B) = \nu(f \in B) = \nu\left(f^{-1}(B)\right), \quad B \in \mathcal{G}$$

If $\nu = P$ is a probability measure and X is a random variable or a random vector, then $P \circ X^{-1}$ is called the *law* or the *distribution* of X and is denoted by P_X .

The c.d.f. of P_X is also called the c.d.f. or joint c.d.f. of X and is denoted by F_X .

Examples 1.3 and 1.4